

GAUSS-MARKOV THEOREM

We have seen that we can derive the estimate $\hat{\beta}$ both as a maximization of the likelihood under the Gaussian linear model assumption (ML estimate) and as a minimization of the sum of squares (OLS estimate), without the need to specify a distribution (and only using conditions on the first two moments).

We consider now the second framework \rightarrow remove the distributive assumption.

Assume that: 1) $\underline{Y} = X \underline{\beta} + \underline{\varepsilon}$ linearity

2) $E[\underline{\varepsilon}] = \underline{0}$ and $\text{var}(\underline{\varepsilon}) = \sigma^2 I_n$ (homoscedasticity and incoherence)

3) X non-stochastic with full rank ($\text{rank}(X) = p$)

The OLS estimator is $\hat{\beta}(Y) = (X^T X)^{-1} X^T Y$ (linear transformation of Y)

Even without the specification of a distribution for Y , we can still derive the first two moments of $\hat{\beta}$.

We have already computed them: $E[\hat{\beta}] = \beta$, $\text{var}(\hat{\beta}) = (X^T X)^{-1} \sigma^2$.
 \downarrow
unbiased

GAUSS-MARKOV THM.

Consider the framework defined by assumptions (1)(2)(3).

Then the OLS estimator $\hat{\beta}(Y)$ is B.L.U.E. (i.e. the Best Linear Unbiased Estimator)

\downarrow "best" = "minimum variance"

So the theorem states that, in the class of linear and unbiased estimators of β , $\hat{\beta}(Y)$ has the minimum variance.

(notice however that it doesn't mean that $\hat{\beta}$ is "the best estimator overall", it is the best only if we restrict to the class of linear and unbiased).

Assume that $\tilde{\beta}(Y)$ is another linear unbiased estimator.

(i.e. $\tilde{\beta}(Y) = A \cdot Y$ and $E[\tilde{\beta}] = \beta$)

The thm states that

$$\text{var}(\tilde{\beta}(Y)) \geq \text{var}(\hat{\beta}(Y))$$